

ND40

servo converter

Technical features

Position feedback systems

- resolver
- sine encoders (with and without commutation track) of various manufacturers
- linear incremental measuring systems of various manufacturers
- rotary absolute measuring systems (single-turn/multi-turn) with Heidenhain ENDAT 2.2 interface
- linear absolute measuring systems with Heidenhain ENDAT 2.2 interface

Bus systems

- control and configuration over PC via serial interface with NOVOBUS protocol
- control and configuration over integrated CAN bus interface with NOVOBUS protocol; setpoint setting over service channel or process data channel; freely selectable configuration of process data read/write telegrams
- extension module "Profibus" for easy PLC connection
- extension module " CANOpen" for easy PLC connection

Other interfaces

- 12 digital inputs
- 6 digital outputs
- 10/12/14 bit analog input
- counter input for setpoint setting over electronic gear or via frequency/direction
- encoder emulation when using a resolver (1 1024 pulses per rotation)

Regulation

- position/speed regulation with/without torque limitation
- immediate switching of regulation mode and setpoint setting mode within 5 ms
- cycle time for regulation of position and speed: 102 μs
- cycle time for current control: 102 μs or 204 μs, respectively

Setpoint setting

Freely selectable from various sources:

- analog setpoint setting for speed
- frequency/direction setpoint setting
- setpoint setting over electronic gear
- digital setpoint setting for speed over bus
- setpoint setting over positioning control in various forms, e.g. relative/absolute setpoint setting, linear ramps, setpoint ramps etc.
- setpoint setting over sequencing control feat. 128 parameter sets